

Torsion

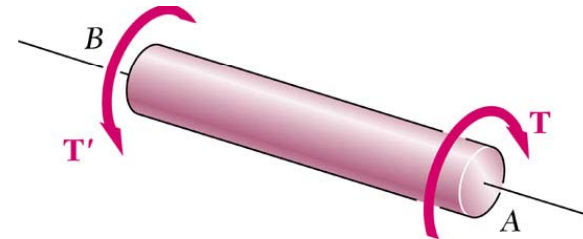
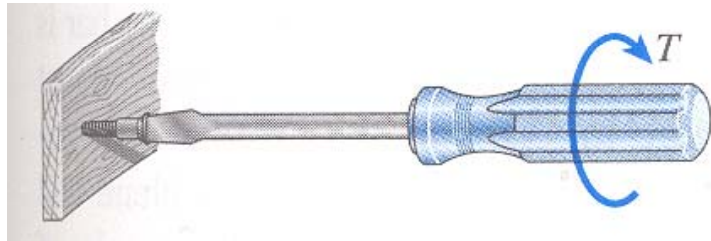
MAE 314 – Solid Mechanics

Y. Zhu

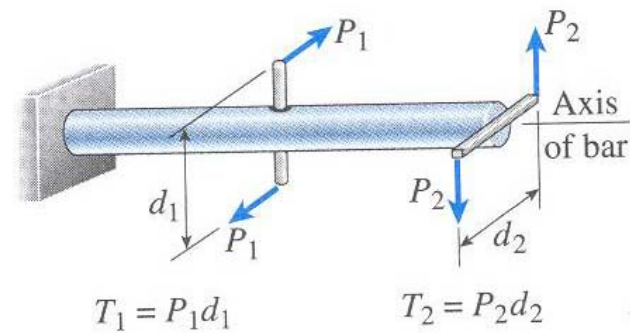
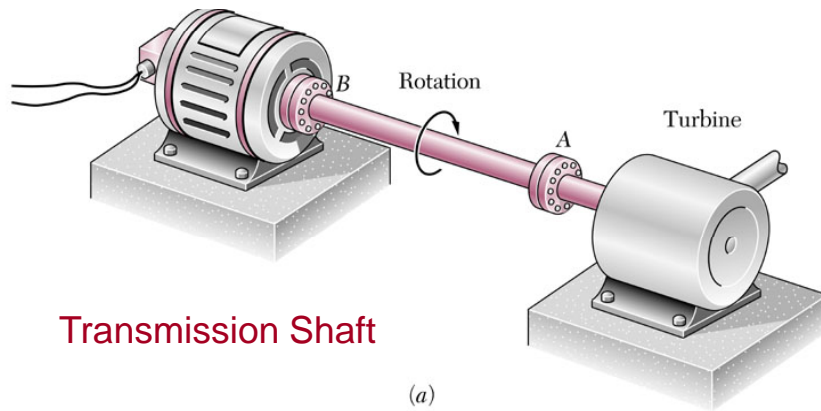


Torsion of Circular Shafts

- In this chapter, we will examine uniaxial bars subject to torque.



- Where does this occur?

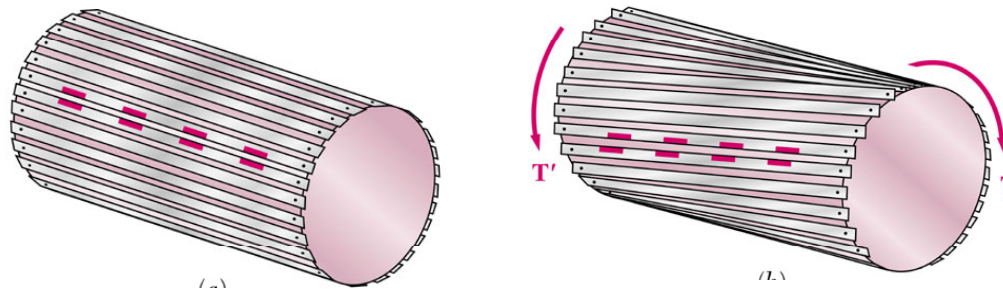


Force Couples

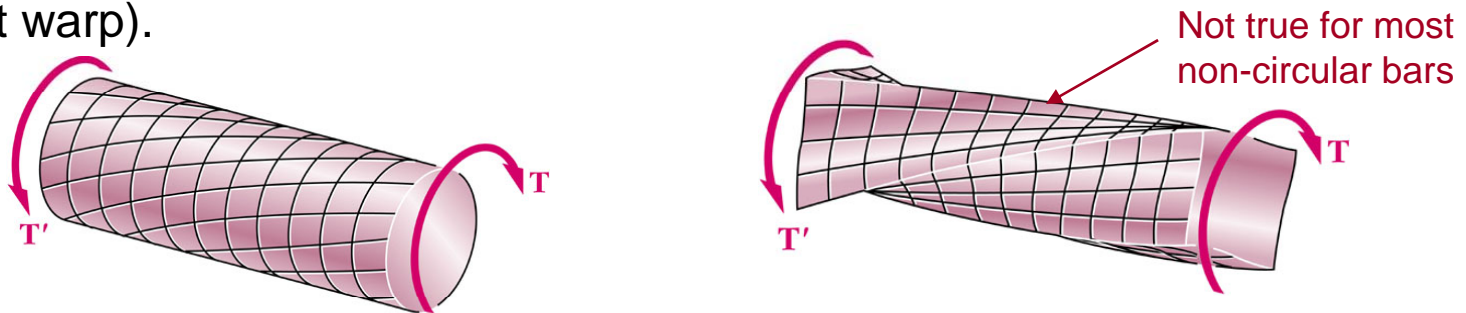


Torsion of Circular Shafts *cont'd*

- We assume
 - Bar is in pure torsion
 - Small rotations (the length and radius will not change)
- How does the bar deform?
 - Cross-section of the bar remains the same shape, bar is simply rotating.



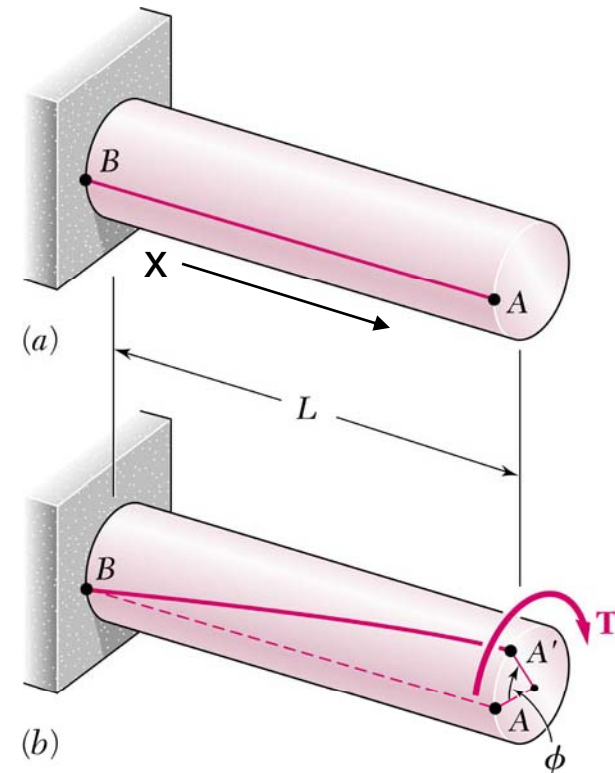
- Cross-section remains perpendicular to axis of cylinder (cylinder does not warp).



Angle of Twist

- Deformation of a circular shaft subjected to pure torsion
 - Fix left end of shaft
 - A moves to A'
 - ϕ = angle of twist (in radians)
- What are the boundary conditions on ϕ ?
 - $\phi(x) = 0$ at $x = 0$
 - $\phi(x) = \phi$ at $x = L$
- For pure torsion, ϕ is linear.

$$\phi(x) = \frac{\phi x}{L}$$



Shearing Strain

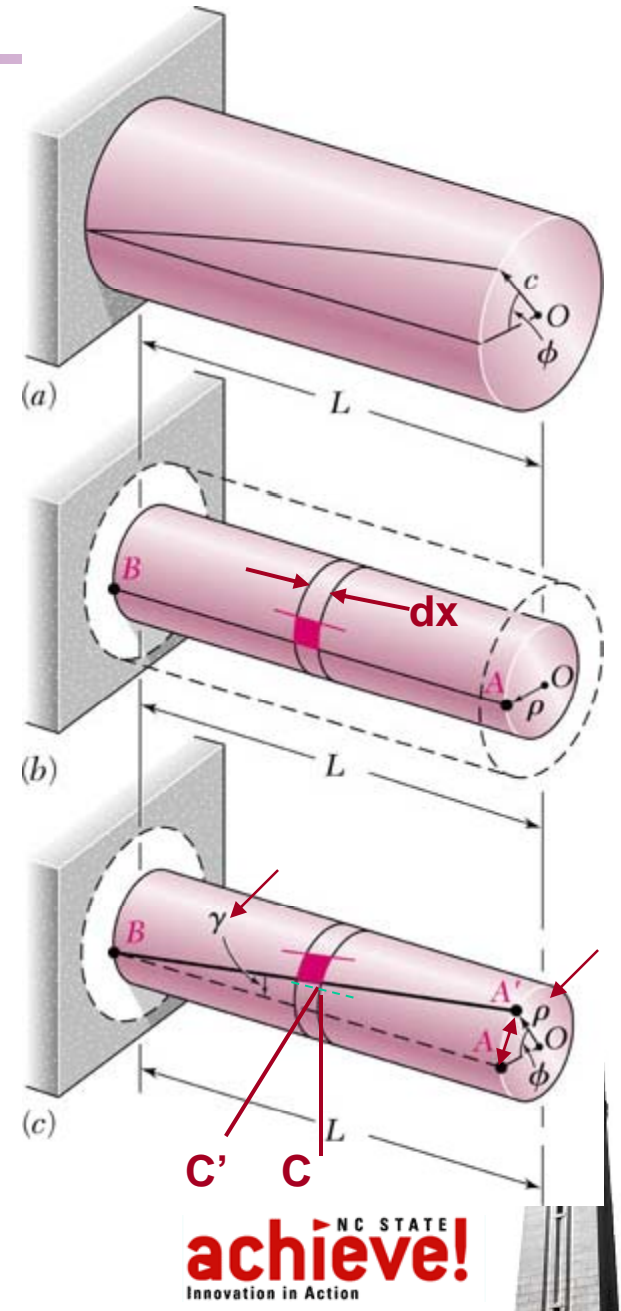
- Calculate the surface shear strain in the cylinder.
- Consider an element of length dx .
- Recall we assume small ϕ & small γ .

$$\gamma = \frac{\overline{C'C}}{dx} \quad \overline{C'C} = \rho d\phi \quad \gamma = \rho \frac{d\phi}{dx}$$

$\frac{d\phi}{dx}$ = rate of change of angle of twist along the bar

- This equation applies to any function $\phi(x)$.
- For pure torsion $\phi(x) = \phi x / L$, so

$$\gamma = \frac{\rho\phi}{L}$$



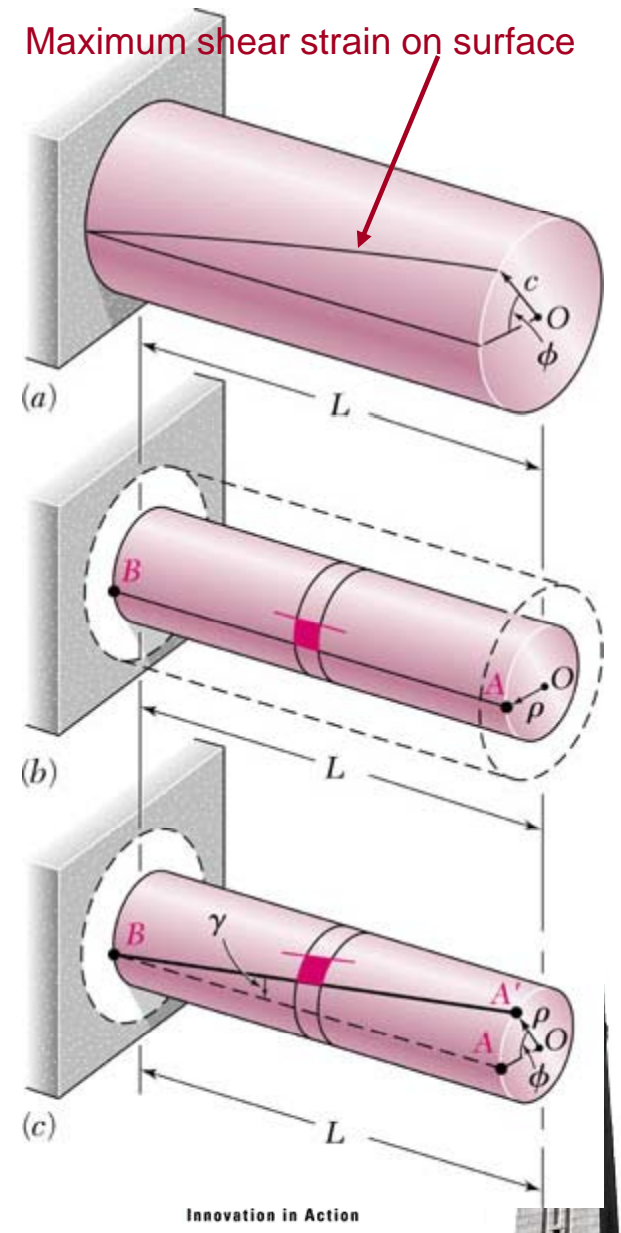
Shearing Strain *cont'd*

- The maximum shear strain on the surface of the cylinder occurs when $\rho=c$.

$$\gamma_{\max} = \frac{c\phi}{L}$$

- We can express the shearing strain at any distance from the axis of the shaft as

$$\gamma = \frac{\rho}{c} \gamma_{\max}$$

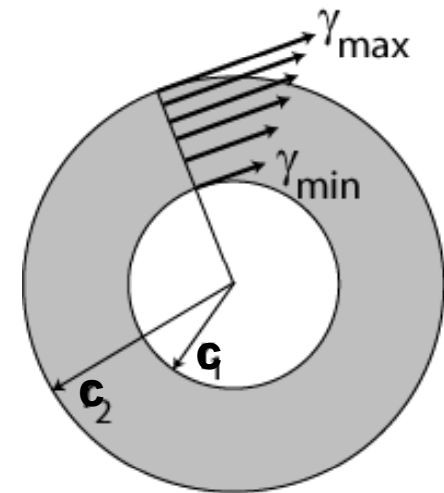


Shearing Strain *cont'd*

- We can also apply the equation for maximum surface shear strain to a hollow circular tube.

$$\gamma_{\min} = \frac{c_1 \phi}{L}$$

$$\gamma_{\max} = \frac{c_2 \phi}{L}$$

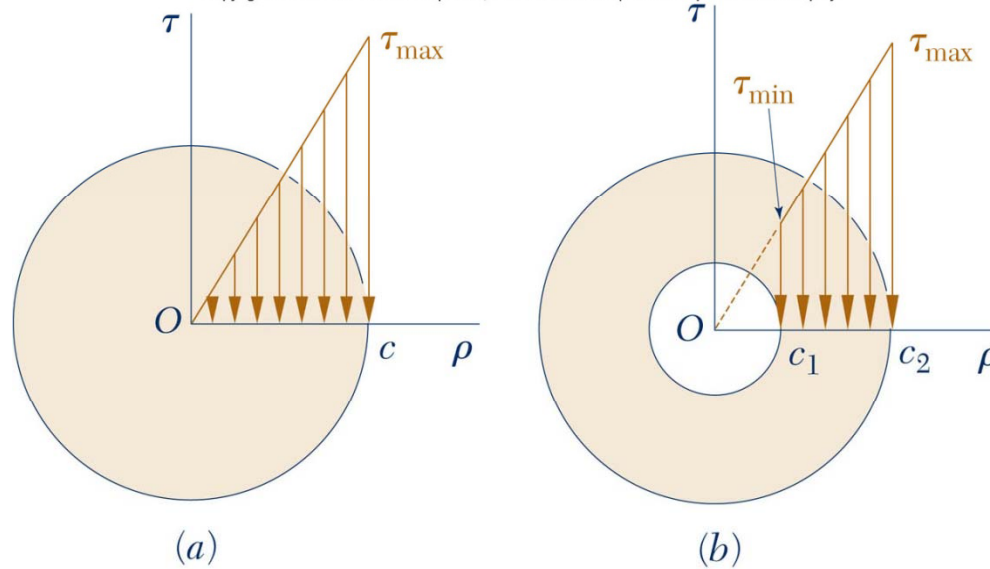


- This applies for all types of materials: elastic, linear, non-linear, plastic, etc.



Elastic Shearing Stress

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- Calculate shear stress in a bar made of linearly elastic material.
- Recall Hooke's Law for shearing stress: $\tau = G\gamma$

$$\tau_{\max} = G\gamma_{\max} = \frac{Gc\phi}{L} \Rightarrow \tau = \frac{\rho}{c} \tau_{\max}$$



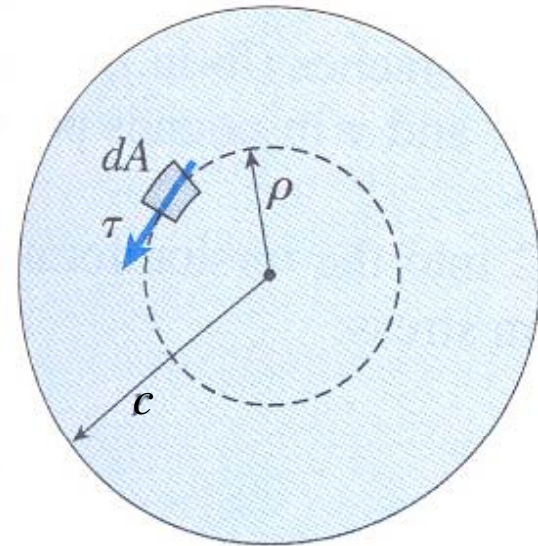
Torque

- We still need to relate τ to the applied torque T , which is generally the known, applied load.
- First, find the resultant moment acting on a cross-section and set this equal to T .

$$\tau = \frac{\rho}{c} \tau_{\max}$$

$$dM = \tau \rho dA = \frac{\rho^2}{c} \tau_{\max} dA$$

$$T = \int_A \frac{\rho^2}{c} \tau_{\max} dA = \frac{\tau_{\max}}{c} \int_A \rho^2 dA$$



Torque *cont'd*

- Continuing from previous slide:

$$T = \frac{\tau_{\max}}{c} \int_A \rho^2 dA = \frac{\tau_{\max}}{c} J \Rightarrow \boxed{\tau_{\max} = \frac{Tc}{J}}, \quad \boxed{\tau = \frac{T\rho}{J}}$$

- Where J is the polar moment of inertia of the cross section of the bar (see Appendix in your textbook).

- Plug this into the equation for τ_{\max} .

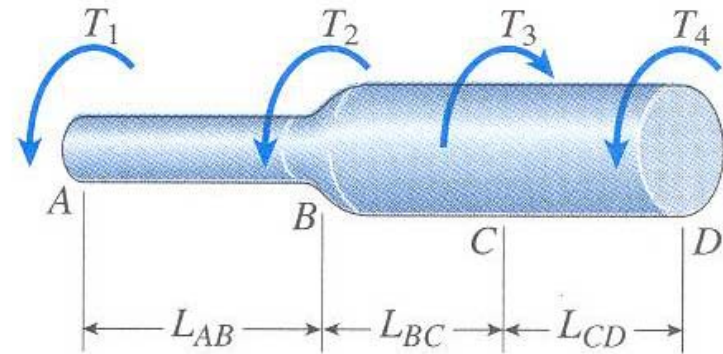
$$\tau_{\max} = \frac{Gc\phi}{L} \rightarrow \frac{Gc\phi}{L} = \frac{Tc}{J} \Rightarrow \boxed{\phi = \frac{TL}{GJ}}$$



Torque *cont'd*

- For a non-uniform bar

$$\phi = \sum_{i=1}^n \phi_i = \sum_{i=1}^n \frac{T_i L_i}{G_i J_i}$$

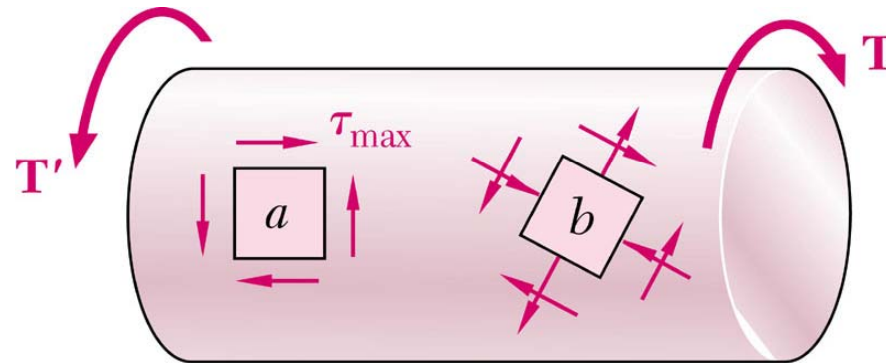


- For a continuously varying bar

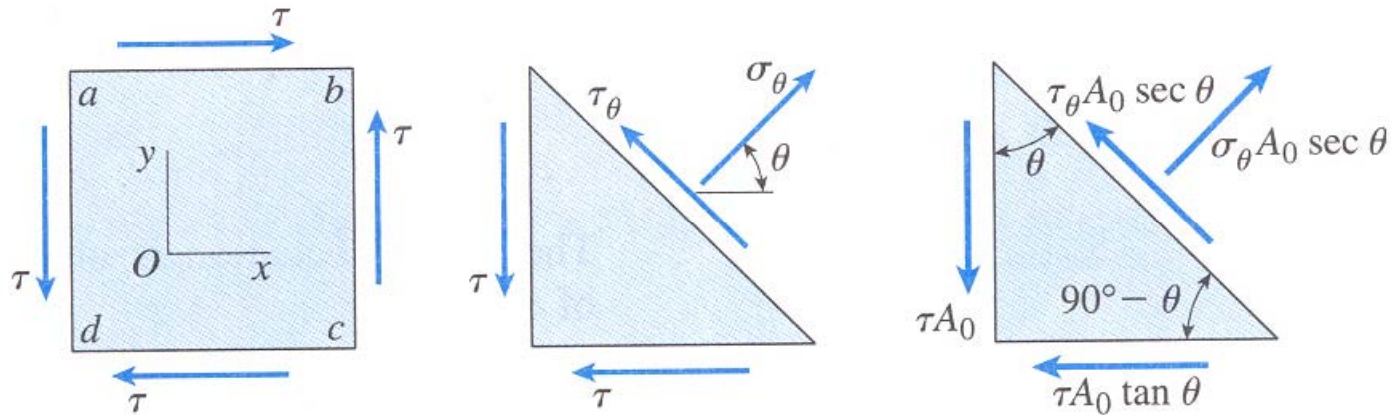
$$\phi = \int_0^L \frac{T(x)}{GJ(x)} dx$$



Inclined Plane



- Cut a rectangular element along the plane at an angle θ .



Inclined Plane *cont'd*

- Sum forces in x-direction.

$$\sigma_{\theta} A_0 \sec \theta - \tau A_0 \sin \theta - \tau A_0 \tan \theta \cos \theta = 0$$

$$\sigma_{\theta} = \tau \sin \theta \cos \theta + \tau \sin \theta \cos \theta$$

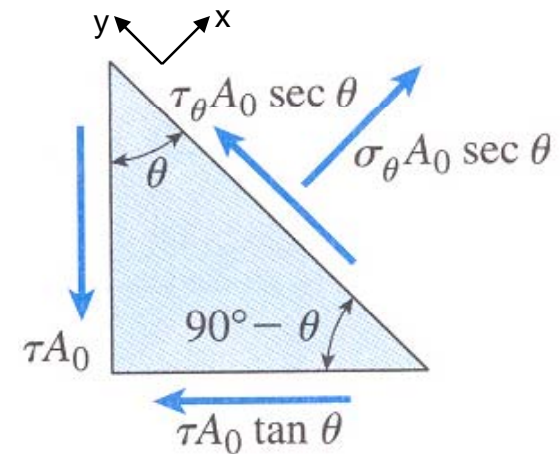
$$\sigma_{\theta} = 2\tau \sin \theta \cos \theta = \tau \sin 2\theta$$

- Sum forces in y-direction.

$$\tau_{\theta} A_0 \sec \theta - \tau A_0 \cos \theta + \tau A_0 \tan \theta \sin \theta = 0$$

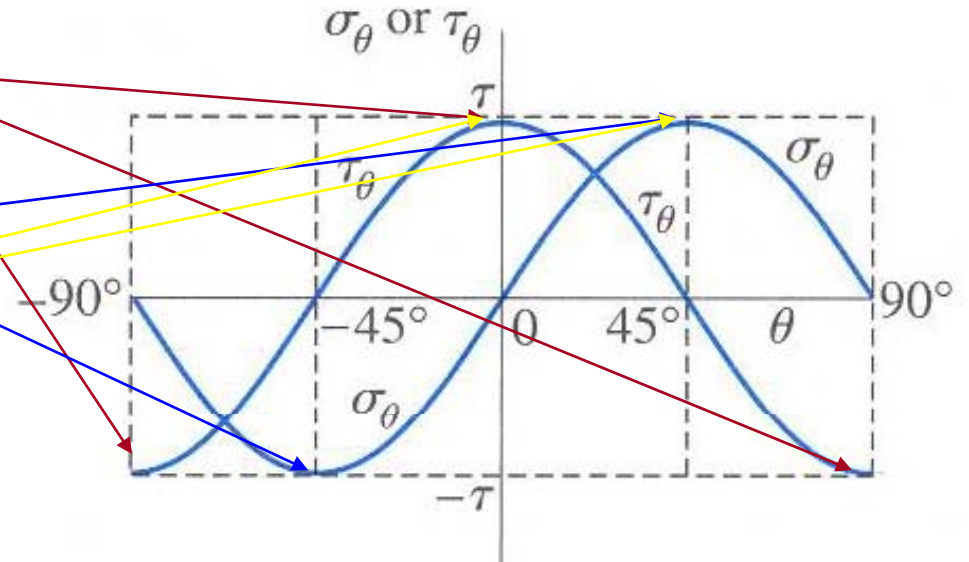
$$\tau_{\theta} = \tau \cos^2 \theta - \tau \sin^2 \theta$$

$$\tau_{\theta} = \tau \cos 2\theta$$

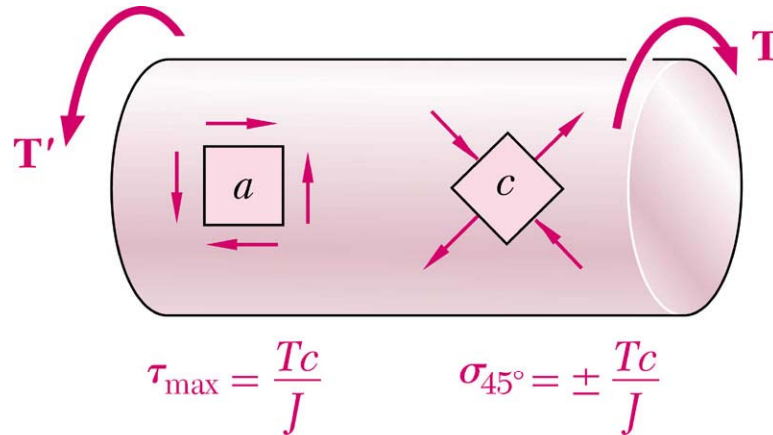


Inclined Plane *cont'd*

- τ_{\max} occurs at $\theta = 0^\circ, \pm 90^\circ$
- σ_{\max} occurs at $\theta = \pm 45^\circ$
- $\tau_{\max} = \sigma_{\max}$



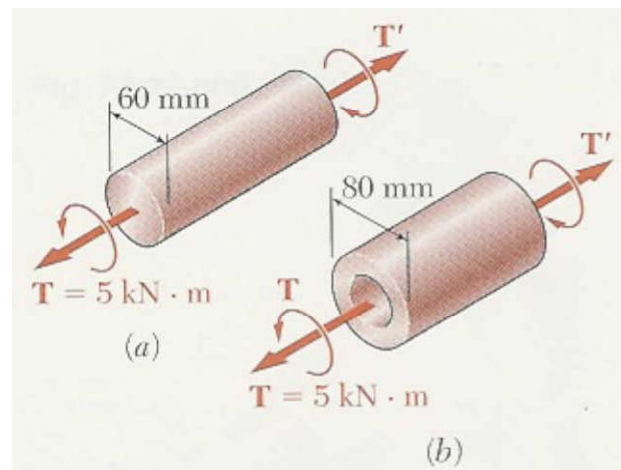
- When σ_θ is max, $\tau_\theta = 0$, and when τ_θ is max, $\sigma_\theta = 0$.



Example Problem 1

Part 1. For the 60 mm diameter solid cylinder and loading shown, determine the maximum shearing stress.

Part 2. Determine the inner diameter of the hollow cylinder, of 80 mm outer diameter, for which the maximum stress is the same as in part 1.



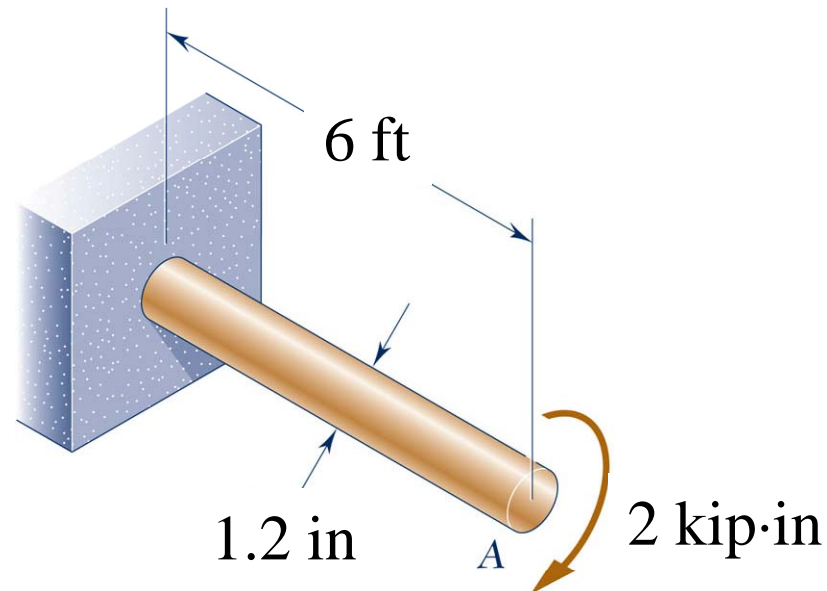


Example Problem 2

Part 1. For the solid steel shaft shown ($G = 11.2 \times 10^6$ psi) determine the angle of twist at A.

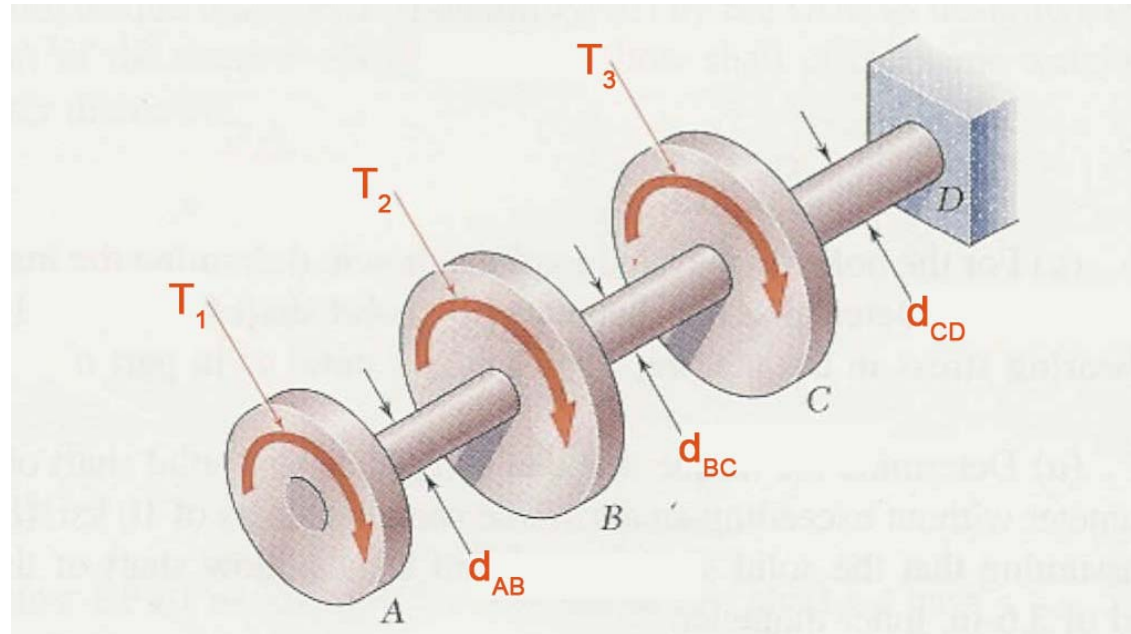
Part 2. Determine the angle of twist at A assuming the steel shaft is hollow with a 1.2 inch outer diameter and 0.8 inch inner diameter.

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Statically Determinate Problems - Example



Find maximum shearing stress in each bar.





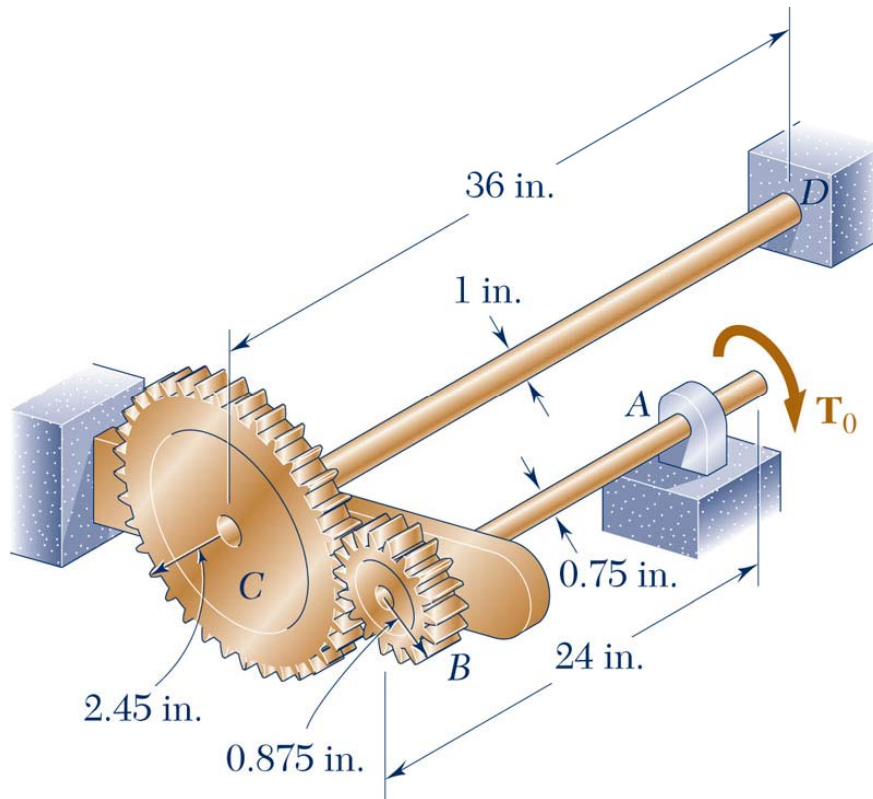
Statically Indeterminate Problems

- Method for torsion is the same as the method for statically indeterminate axial load deflection problems.
- Apply what you've already learned:
 - **$M = R - N$**
 - M = number of compatibility equations needed
 - R – number of unknown reactions (or internal stresses)
 - N = number of equilibrium equations
- Compatibility equations for a torsion problem are based on angle of twist.



Statically Indeterminate Problems - Example

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Given:

$$L_{CD} = 36 \text{ in.}, d_{CD} = 1 \text{ in.}$$

$$r_C = 2.45 \text{ in.}, r_B = 0.875 \text{ in.}$$

$$L_{AB} = 24 \text{ in.}, d_{AB} = 0.75 \text{ in.}$$

$$G = 11.2 \times 10^6 \text{ psi}$$

The allowable shear stress is 8 ksi

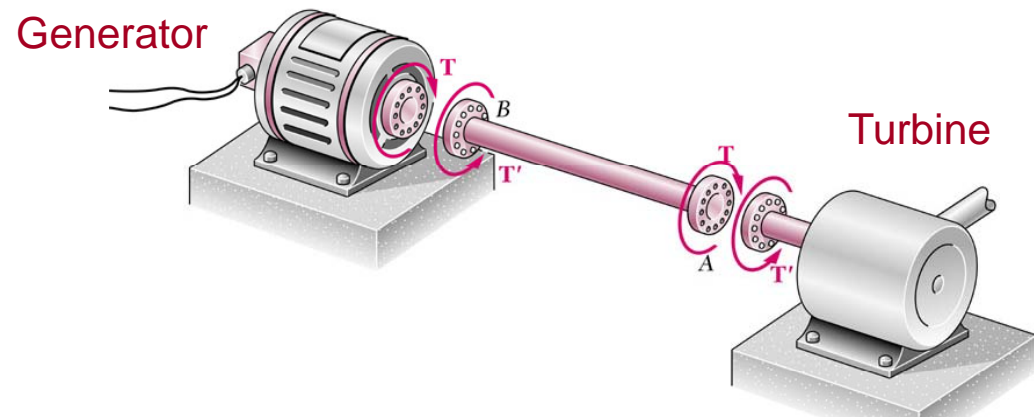
Find the largest torque T_0 that can be applied to the end of shaft AB and the angle of rotation of the end A of shaft AB.





Transmission Shafts

- In a transmission, a circular shaft transmits mechanical power from one device to another.



- ω = angular speed of rotation of the shaft
- The shaft applies a torque T to another device
- To satisfy equilibrium the other device applies torque T to the shaft.
- The power transmitted by the shaft is

$$P = T\omega$$



Transmission Shafts *cont'd*

- Units for $P=T\omega$
 - $\omega = \text{rad/s}$
 - $T = \text{N}\cdot\text{m}$ (SI)
 - $T = \text{ft}\cdot\text{lb}$ (English)
 - $P = \text{Watts}$ ($1 \text{ W} = 1 \text{ N}\cdot\text{m/s}$) (SI)
 - $P = \text{ft}\cdot\text{lb/s}$ ($1 \text{ horsepower} = \text{hp} = 550 \text{ ft}\cdot\text{lb/s}$) (English)
- We can also express power in terms of frequency.

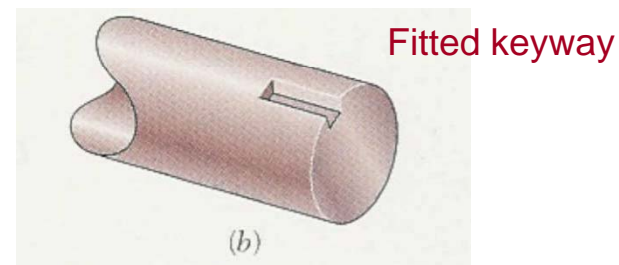
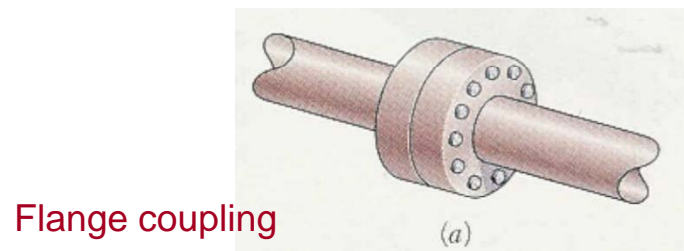
$$\omega = 2\pi f \quad f = \text{Hz} = \text{s}^{-1}$$

$$P = 2\pi f T$$



Stress Concentrations in Circular Shafts

- Up to now, we assumed that transmission shafts are loaded at the ends through solidly attached, rigid end plates.
- In practice, torques are applied through flange couplings and fitted keyways, which produce high stress concentrations.



- One way to reduce stress concentrations is through the use of a fillet.



Stress Concentrations in Circular Shafts *cont'd*

- Maximum shear stress at the fillet

$$\tau_{\max} = K \frac{Tc}{J}$$

- Tc/J is calculated for the smaller-diameter shaft
- K = stress concentration factor

