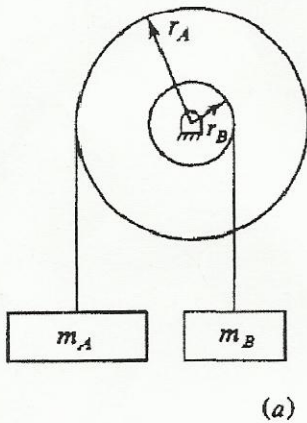
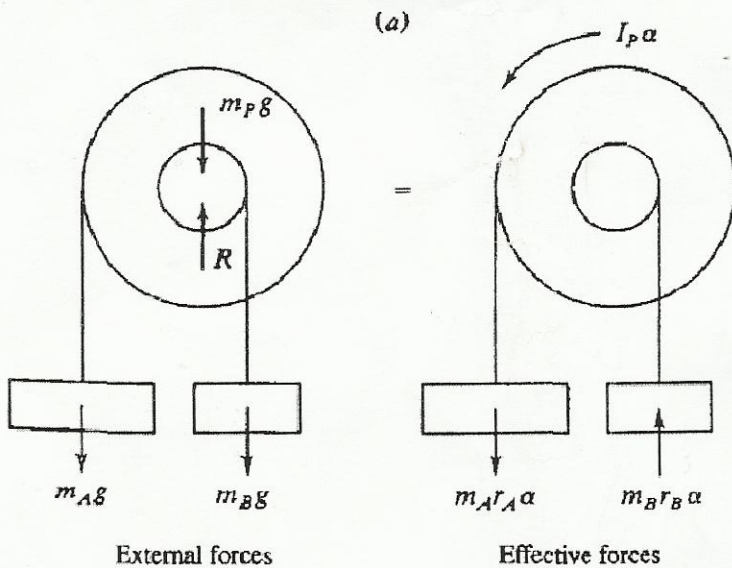


**Q1** Determine the angular acceleration of the pulley



**Solution**



$$\sum Mo_{ext} = \sum Mo_{eff}$$

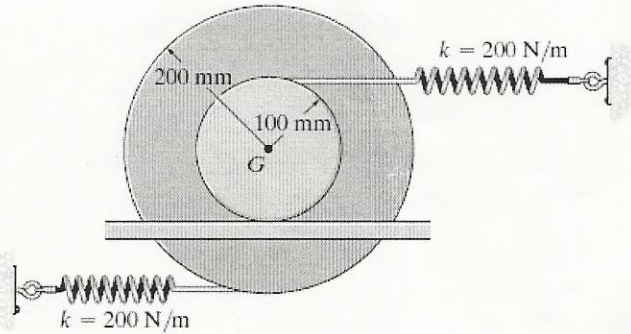
$$m_A g r_A - m_B g r_B = I_p \alpha + m_A r_A^2 \alpha + m_B r_B^2 \alpha$$

Where:  $r_A = 30\text{cm}$ ;  $r_B = 20\text{cm}$ ;  $I_p = 0.6\text{kg}\cdot\text{m}^2$ ;  $m_A = 5\text{kg}$ ;  $m_B = 3\text{kg}$

$$\alpha = \frac{m_A g r_A - m_B g r_B}{I_p + m_A r_A^2 + m_B r_B^2}$$

$$\alpha = 7.55\text{rad} / \text{s}^2$$

**Q2** Determine the differential equation of motion of the 15-kg spool. Assume that it does not slip at the surface of contact as it oscillates. The radius of gyration of the spool about its center of mass is  $K_G=125\text{mm}$ . The springs are originally unstretched.



**solution**

Energy Equation: Since the spool rolls without slipping, the stretching of both springs can be approximated as  $x_1=0.1\theta$  and  $x_2=0.2\theta$  when the spool is being displaced by a small angular displacement  $\theta$ . Thus the elastic potential energy is

$$V_p = \frac{1}{2} kx_1^2 + \frac{1}{2} kx_2^2$$

$$= \frac{1}{2} (200)(0.1\theta)^2 + \frac{1}{2} (200)(0.2\theta)^2 = 5\theta^2$$

$$V = V_e = 5\theta^2$$

The mass moment of the spool about A is  $I_A$

$$I_A = 15(0.125^2) + 15(0.1^2) = 0.384375 \text{ kg.m}^2$$

The kinetic energy is

$$T = \frac{1}{2} I_A \omega^2 = \frac{1}{2} (0.384375) \dot{\theta}^2 = 0.1921875 \dot{\theta}^2$$

The total energy of the system is

$$U = T + V = 0.1921875 \dot{\theta}^2 + 5\theta^2$$

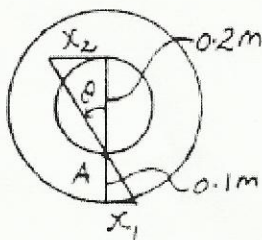
Time derivative : taking the time derivative of above eqn we have;

$$0.384375 \ddot{\theta} \theta + 10\theta \dot{\theta} = 0$$

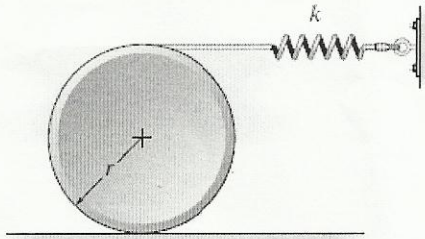
$$\dot{\theta} (0.384375 \ddot{\theta} + 10\dot{\theta}) = 0$$

since  $\dot{\theta} \neq 0$ , then the term in brackets  $\rightarrow 0.384375 \ddot{\theta} + 10\dot{\theta} = 0$

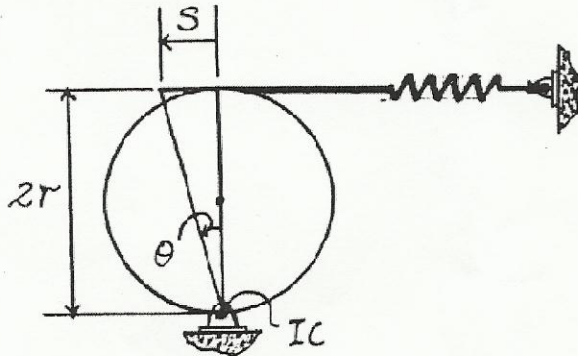
$$\ddot{\theta} + 26.0\dot{\theta} = 0 \text{ [ANS]}$$



Q3 Determine the natural period of vibration of the disk having a mass 50kg and radius 200mm. Assume the disk does not slip on the surface of contact as it oscillates. Spring constant  $k = 200 \text{ N/m}$



**SOLUTION**



$T + V = \text{Constant}$

$s = (2r)\theta$

$T + V = \frac{1}{2} \left[ \frac{1}{2}mr^2 + mr^2 \right] \dot{\theta}^2 + \frac{1}{2}k(2r\theta)^2 \dots\dots\dots(1)$

Taking time derivative of eqn 1, we have

$0 = \left[ \frac{1}{2}mr^2 + mr^2 \right] (2\dot{\theta}\ddot{\theta}) + 8kr^2\theta\dot{\theta}$

$mr^2\dot{\theta}\ddot{\theta} + 2mr^2\dot{\theta}\ddot{\theta} + 8kr^2\theta\dot{\theta} = 0 \rightarrow 3mr^2\dot{\theta}\ddot{\theta} + 8kr^2\theta\dot{\theta} = 0$

$\ddot{\theta} + \frac{8k}{3m}\theta = 0 \rightarrow$  This is a standard 2nd order diff eqn

Thus  $\omega_n = \sqrt{\frac{8k}{3m}} = \sqrt{\frac{8 \times 200}{50}} = 3.26599 \text{ rad/s}$

period  $\tau = \frac{2\pi}{\omega_n} = \frac{2\pi}{3.26599}$

$\tau = 1.92 \text{ sec}$